

Revealed Political Power

Jinhui Bai and Roger Lagunoff

(Georgetown University)

(Georgetown University)

November, 2010

Introduction

- ▶ **Political equality/egalitarianism** is an ingrained governing philosophy in most democracies.

Introduction

- ▶ **Political equality/egalitarianism** is an ingrained governing philosophy in most democracies.
- ▶ The principle is used to judge a government's legitimacy.

Introduction

- ▶ **Political equality/egalitarianism** is an ingrained governing philosophy in most democracies.
- ▶ The principle is used to judge a government's legitimacy.
- ▶ ... embodied in rhetoric.

“one-man-one-vote”, “justice is blind”, “equality in the eyes of the law” - Cleisthenes, 508BC, etc.,...

Wealth Bias?

- ▶ **Channels of Wealth Bias in Policy Making Process.**
 - ▶ **Differential participation rates.** Rosenstone and Hansen (1993), Bartels (2008).

Wealth Bias?

- ▶ **Channels of Wealth Bias in Policy Making Process.**
 - ▶ **Differential participation rates.** Rosenstone and Hansen (1993), Bartels (2008).
 - ▶ **Political Knowledge and Contact.** Bartels (2008).

Wealth Bias?

- ▶ **Channels of Wealth Bias in Policy Making Process.**
 - ▶ **Differential participation rates.** Rosenstone and Hansen (1993), Bartels (2008).
 - ▶ **Political Knowledge and Contact.** Bartels (2008).
 - ▶ **Campaign contributions.** Austen-Smith (1987), Grossman and Helpman (1996), Prat (2002), Coate (2004), Campante (2008).

Research Agenda

- ▶ **Our Focus: Identify Wealth Bias from Policy Outcome:**
 - ▶ When can wealth bias be inferred?
 - ▶ How much wealth bias can be inferred?

Research Agenda

- ▶ **Our Focus: Identify Wealth Bias from Policy Outcome:**
 - ▶ When can wealth bias be inferred?
 - ▶ How much wealth bias can be inferred?
- ▶ **Methodology:**

Non-parametric approach from Revealed Preference Tradition

Research Agenda

- ▶ **Our Focus: Identify Wealth Bias from Policy Outcome:**
 - ▶ When can wealth bias be inferred?
 - ▶ How much wealth bias can be inferred?
- ▶ **Methodology:**

Non-parametric approach from Revealed Preference Tradition
- ▶ **Contrast with Existing Literature:**
 - ▶ *Implication from Parametric Models:*

Benabou (2000), Campante (2008), Bai & Lagunoff (2010)
 - ▶ *Reduced Form Statistical Analysis:* Bartels (2008)

The Revealed-Preference-Type “Thought Experiment”

The Revealed-Preference-Type “Thought Experiment”

- ▶ Adopt point of view of **outside observer** (Afriat (1967), etc...). The observer observes the policy data and the income distribution over a finite horizon.

The Revealed-Preference-Type “Thought Experiment”

- ▶ Adopt point of view of **outside observer** (Afriat (1967), etc...). The observer observes the policy data and the income distribution over a finite horizon.
- ▶ The observer does not observe preference profiles directly, but knows voting preferences are well ordered by income (single crossing restriction).

The Revealed-Preference-Type “Thought Experiment”

- ▶ Adopt point of view of **outside observer** (Afriat (1967), etc...). The observer observes the policy data and the income distribution over a finite horizon.
- ▶ The observer does not observe preference profiles directly, but knows voting preferences are well ordered by income (single crossing restriction).
- ▶ Observer draws inferences about distribution of political power *as if* this distribution was explicitly part of a weighted voting procedure. **Bias = weights** (Benabou, 1996, 2000).

The Revealed-Preference-Type “Thought Experiment”

- ▶ Adopt point of view of **outside observer** (Afriat (1967), etc...). The observer observes the policy data and the income distribution over a finite horizon.
- ▶ The observer does not observe preference profiles directly, but knows voting preferences are well ordered by income (single crossing restriction).
- ▶ Observer draws inferences about distribution of political power *as if* this distribution was explicitly part of a weighted voting procedure. **Bias = weights** (Benabou, 1996, 2000).

Three “Thought Experiments”

1. **The Benchmark Case:** Minimal preference restriction. Only policy data observed.

Three “Thought Experiments”

1. **The Benchmark Case:** Minimal preference restriction. Only policy data observed.

Result: All biases rationalize all policy data.

Three “Thought Experiments”

1. **The Benchmark Case:** Minimal preference restriction. Only policy data observed.

Result: All biases rationalize all policy data.

2. *Expanded Data Set.*

3. **Contracted Set of Allowed Preference.**

Three “Thought Experiments”

1. **The Benchmark Case:** Minimal preference restriction. Only policy data observed.

Result: All biases rationalize all policy data.

2. **Expanded Data Set.** Add polling data.

Result: Upper and lower bounds on bias are derived. Data can sometimes discern “populist” vs “elitist” bias.

3. **Contracted Set of Allowed Preference.**

Three “Thought Experiments”

1. **The Benchmark Case:** Minimal preference restriction. Only policy data observed.

Result: All biases rationalize all policy data.

2. **Expanded Data Set.** Add polling data.

Result: Upper and lower bounds on bias are derived. Data can sometimes discern “populist” vs “elitist” bias.

3. **Contracted Set of Allowed Preference.** Add Preference Restrictions: supermodularity and “weakly separable utility”

Result: unbiased polity imposes monotonicity restriction on the data.

The Economic Side

- ▶ $i \in [0, 1]$ citizen-types.

The Economic Side

- ▶ $i \in [0, 1]$ citizen-types.
- ▶ $T < \infty$ observation dates.

The Economic Side

- ▶ $i \in [0, 1]$ citizen-types.
- ▶ $T < \infty$ observation dates.
- ▶ Observed policies $\{\mathbf{a}_1, \dots, \mathbf{a}_T\}$. (e.g., tax rates, transfers, public goods, etc).

The Economic Side

- ▶ $i \in [0, 1]$ citizen-types.
- ▶ $T < \infty$ observation dates.
- ▶ Observed policies $\{\mathbf{a}_1, \dots, \mathbf{a}_T\}$. (e.g., tax rates, transfers, public goods, etc).
- ▶ States $\{\omega_1, \dots, \omega_T\}$. (e.g. physical capital, human capital, etc.).

The Economic Side

- ▶ $i \in [0, 1]$ citizen-types.
- ▶ $T < \infty$ observation dates.
- ▶ Observed policies $\{\mathbf{a}_1, \dots, \mathbf{a}_T\}$. (e.g., tax rates, transfers, public goods, etc).
- ▶ States $\{\omega_1, \dots, \omega_T\}$. (e.g. physical capital, human capital, etc.).
- ▶ Income distribution. $\mathbf{y}(i, \omega_t)$, $t = 1, \dots, T$.

The Economic Side

- ▶ $\mathbf{i} \in [0, 1]$ citizen-types.
- ▶ $\mathbf{T} < \infty$ observation dates.
- ▶ Observed policies $\{\mathbf{a}_1, \dots, \mathbf{a}_T\}$. (e.g., tax rates, transfers, public goods, etc).
- ▶ States $\{\omega_1, \dots, \omega_T\}$. (e.g. physical capital, human capital, etc.).
- ▶ Income distribution. $\mathbf{y}(\mathbf{i}, \omega_t)$, $t = 1, \dots, T$.

Assumptions: One dimensional policies, states. Each state is distinct. \mathbf{y} increasing in \mathbf{i} , and its structure is known/observed by outside observer.

Preferences

$U(\mathbf{i}, \omega_t, \mathbf{a}_t)$ = \mathbf{i} 's payoff fnc't. Outside observer does not know/observe \mathbf{U} directly, but knows that \mathbf{U} belongs to an "admissible" class defined by

(A1) (Single peakedness) \mathbf{U} single peaked in \mathbf{a} .

(A2) (Single Crossing) \mathbf{U} satisfies single crossing in $(\mathbf{a}; \mathbf{i})$.

A Static Example

$$u(c_t, G_t) = c_t + \frac{G_t^{1-\rho}}{1-\rho} \quad \text{s.t.}$$

$$c_t = (1 - \tau_t) y(i, \omega_t),$$

$$G_t = \tau_t \int_0^1 y(i, \omega_t) di = \tau_t \bar{y}(\omega_t)$$

A Static Example

$$\begin{aligned}u(\mathbf{c}_t, \mathbf{G}_t) &= \mathbf{c}_t + \frac{\mathbf{G}_t^{1-\rho}}{1-\rho} \quad \text{s.t.} \\ \mathbf{c}_t &= (1 - \tau_t) \mathbf{y}(i, \omega_t), \\ \mathbf{G}_t &= \tau_t \int_0^1 \mathbf{y}(i, \omega_t) \, di = \tau_t \bar{\mathbf{y}}(\omega_t)\end{aligned}$$

Define $\mathbf{a}_t = 1 - \tau_t$ so the problem becomes

$$\mathbf{U}(i, \omega_t, \mathbf{a}_t) = \mathbf{a}_t \mathbf{y}(i, \omega_t) + \frac{[(1 - \mathbf{a}_t) \bar{\mathbf{y}}(\omega_t)]^{1-\rho}}{1-\rho}.$$

A Static Example

$$\begin{aligned}u(\mathbf{c}_t, \mathbf{G}_t) &= \mathbf{c}_t + \frac{\mathbf{G}_t^{1-\rho}}{1-\rho} \quad \text{s.t.} \\ \mathbf{c}_t &= (1 - \tau_t) \mathbf{y}(\mathbf{i}, \omega_t), \\ \mathbf{G}_t &= \tau_t \int_0^1 \mathbf{y}(\mathbf{i}, \omega_t) d\mathbf{i} = \tau_t \bar{\mathbf{y}}(\omega_t)\end{aligned}$$

Define $\mathbf{a}_t = 1 - \tau_t$ so the problem becomes

$$\mathbf{U}(\mathbf{i}, \omega_t, \mathbf{a}_t) = \mathbf{a}_t \mathbf{y}(\mathbf{i}, \omega_t) + \frac{[(1 - \mathbf{a}_t) \bar{\mathbf{y}}(\omega_t)]^{1-\rho}}{1-\rho}.$$

Problem accommodates:

- (a) pure growth. $\mathbf{y}(\mathbf{i}, \omega_t) = \mathbf{g}(\mathbf{i})\omega_t$.
- (b) pure (mean-preserving) inequality change. $\bar{\mathbf{y}}(\omega) = \bar{\mathbf{y}}$.

The Political Side

Power is measured by a *wealth-weighted vote share* $\lambda(\mathbf{y}, \alpha, \omega)$
where $\alpha(\omega) = \textit{bias}$ in each state.

The Political Side

Power is measured by a *wealth-weighted vote share* $\lambda(\mathbf{y}, \alpha, \omega)$ where $\alpha(\omega) = \textit{bias}$ in each state.

Canonical case (Benabou (1996, 2000)):

$$\lambda(\mathbf{y}(\mathbf{i}, \omega), \alpha(\omega), \omega) = \frac{\mathbf{y}(\mathbf{i}, \omega)^{\alpha(\omega)}}{\int_0^1 \mathbf{y}(\mathbf{j}, \omega)^{\alpha(\omega)} d\mathbf{j}} = \frac{\mathbf{y}(\mathbf{i}, \omega)^{\alpha(\omega)} \mathbf{1}^{1-\alpha(\omega)}}{\int_0^1 \mathbf{y}(\mathbf{j}, \omega)^{\alpha(\omega)} \mathbf{1}^{1-\alpha(\omega)} d\mathbf{j}}$$

The Political Side

Power is measured by a *wealth-weighted vote share* $\lambda(\mathbf{y}, \alpha, \omega)$ where $\alpha(\omega) = \textit{bias}$ in each state.

Canonical case (Benabou (1996, 2000)):

$$\lambda(\mathbf{y}(\mathbf{i}, \omega), \alpha(\omega), \omega) = \frac{\mathbf{y}(\mathbf{i}, \omega)^{\alpha(\omega)}}{\int_0^1 \mathbf{y}(\mathbf{j}, \omega)^{\alpha(\omega)} d\mathbf{j}} = \frac{\mathbf{y}(\mathbf{i}, \omega)^{\alpha(\omega)} \mathbf{1}^{1-\alpha(\omega)}}{\int_0^1 \mathbf{y}(\mathbf{j}, \omega)^{\alpha(\omega)} \mathbf{1}^{1-\alpha(\omega)} d\mathbf{j}}$$

$\alpha(\omega) =$ weight attached to voter's relative wealth.

$1 - \alpha(\omega) =$ weight attached to *equal representation*.

The Political Side

Power is measured by a *wealth-weighted vote share* $\lambda(\mathbf{y}, \alpha, \omega)$ where $\alpha(\omega) = \textit{bias}$ in each state.

Canonical case (Benabou (1996, 2000)):

$$\lambda(\mathbf{y}(i, \omega), \alpha(\omega), \omega) = \frac{\mathbf{y}(i, \omega)^{\alpha(\omega)}}{\int_0^1 \mathbf{y}(j, \omega)^{\alpha(\omega)} dj} = \frac{\mathbf{y}(i, \omega)^{\alpha(\omega)} \mathbf{1}^{1-\alpha(\omega)}}{\int_0^1 \mathbf{y}(j, \omega)^{\alpha(\omega)} \mathbf{1}^{1-\alpha(\omega)} dj}$$

$\alpha(\omega) = \textit{weight}$ attached to voter's relative wealth.

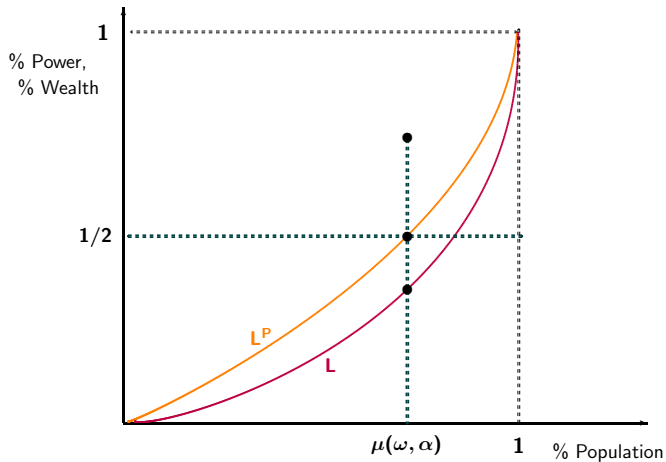
$1 - \alpha(\omega) = \textit{weight}$ attached to *equal representation*.

$\alpha(\omega) > 0$ an *elitist bias*

$\alpha(\omega) < 0$ a *populist bias*

$\alpha(\omega) = 0$ an *unbiased polity*.

Political Lorenz Curve with Elitist Bias



Weighted Majority Winners

Def'n A policy \mathbf{a} is an α -Weighted Majority Winner (WMW) in state ω under admissible profile \mathbf{U} if,

$$\int_{\{i: U(i, \omega, \mathbf{a}) \geq U(i, \omega, \hat{\mathbf{a}})\}} \lambda(\mathbf{y}(i, \omega), \alpha(\omega), \omega) \, d\mathbf{i} \geq 1/2 \quad \forall \hat{\mathbf{a}}$$

Rationalizing Policy Data

Policy rule $\Psi(\omega) = \mathbf{a}$.

Rationalizing Policy Data

Policy rule $\Psi(\omega) = \mathbf{a}$.

Def'n A weighting function α *rationalizes the policy data* $\{\mathbf{a}_t\}_{t=1}^T$ if \exists admissible profile \mathbf{U} and policy rule Ψ consistent with the data such that for each ω , $\Psi(\omega)$ is an α -Weighted Majority Winner under \mathbf{U} .

A Benchmark

A Benchmark

“Anything Goes” Theorem

Let $\{\mathbf{a}_t\}_{t=1}^T$ be any policy data and α be any weighting function.
Then α rationalizes $\{\mathbf{a}_t\}_{t=1}^T$.

A Benchmark

“Anything Goes” Theorem

*Let $\{\mathbf{a}_t\}_{t=1}^T$ be any policy data and α be any weighting function.
Then α rationalizes $\{\mathbf{a}_t\}_{t=1}^T$.*

Bottom line: any distribution of political power - including one implied by equal representation (an unbiased polity) - can rationalize the policy data.

- ▶ Prf is constructive. Apply Gans-Smart Med. Voter Thm. Then construct admissible preference profile (adapt Boldrin-Montrucchio quadratic form).

$$U(i, \omega, \mathbf{a}; \Psi) = -\frac{1}{2} \left(\mathbf{a} - \tilde{\Psi}(i, \omega) \right)^2,$$

where $\tilde{\Psi}(\mu(\omega, \alpha), \omega) = \Psi(\omega)$.

Polling Data

- ▶ **N** polls taken at each **t** comparing \mathbf{a}_t to policy alternatives

$$\mathbf{a}^1 < \mathbf{a}^2 < \dots < \mathbf{a}^N$$

Polling Data

- ▶ **N** polls taken at each **t** comparing **a_t** to policy alternatives

$$\mathbf{a}^1 < \mathbf{a}^2 < \dots < \mathbf{a}^N$$

- ▶ Poll data: Fraction **p_tⁿ** of population prefer **a_t** to policy alternative **aⁿ**.

Polling Data

- ▶ **N** polls taken at each **t** comparing **a_t** to policy alternatives

$$\mathbf{a}^1 < \mathbf{a}^2 < \dots < \mathbf{a}^N$$

- ▶ Poll data: Fraction **p_tⁿ** of population prefer **a_t** to policy alternative **aⁿ**.
- ▶ No measurement error (!!).

Def'n An α rationalizes both policy data $\{\mathbf{a}_t\}_{t=1}^T$ and poll data $\{\mathbf{p}_t^n\}_{t=1, n=1}^{T, N}$ if \exists admissible \mathbf{U} and Ψ consistent with the data such that

- (i) $\forall \omega$, $\Psi(\omega)$ is an α -Weighted Majority Winner under \mathbf{U} ,
and
- (ii) $\forall t \ \forall n$, \mathbf{U} satisfies

$$\mathbf{p}_t^n = |\{i : \mathbf{U}(i, \omega_t, \mathbf{a}_t) \geq \mathbf{U}(i, \omega_t, \mathbf{a}^n)\}|$$

Polling Result

Let n_t^* satisfy $a^{n_t^*-1} < a_t < a^{n_t^*}$

$a^{n_t^*-1}$ = closest “left-wing” alternative.

$a^{n_t^*}$ = closest “right-wing” alternative.

Polling Result

Let n_t^* satisfy $a_t^{n_t^*-1} < a_t < a_t^{n_t^*}$

$a_t^{n_t^*-1}$ = closest “left-wing” alternative.

$a_t^{n_t^*}$ = closest “right-wing” alternative.

Theorem

Let $\{a_t\}$ be any policy data and $\{p_t^n\}_{t=1, n=1}^{T, N}$ any arbitrary polling data. Then:

1. There exists an α that rationalizes the data iff $\forall t$,
 $1 - p_t^1 < \dots < 1 - p_t^{n_t^*-2} < 1 - p_t^{n_t^*-1} < p_t^{n_t^*} < p_t^{n_t^*+1} < \dots < p_t^N$

Polling Result

Let n_t^* satisfy $a^{n_t^*-1} < a_t < a^{n_t^*}$

$a^{n_t^*-1}$ = closest “left-wing” alternative.

$a^{n_t^*}$ = closest “right-wing” alternative.

Theorem

Let $\{a_t\}$ be any policy data and $\{p_t^n\}_{t=1, n=1}^{T, N}$ any arbitrary polling data. Then:

1. There exists an α that rationalizes the data iff $\forall t$,

$$1 - p_t^1 < \dots < 1 - p_t^{n_t^*-2} < 1 - p_t^{n_t^*-1} < p_t^{n_t^*} < p_t^{n_t^*+1} < \dots < p_t^N$$

2. Any given α rationalizes the data iff

$$1 - p_t^1 < \dots < 1 - p_t^{n_t^*-2} < 1 - p_t^{n_t^*-1} < \mu(\omega_t, \alpha) < p_t^{n_t^*} \\ < p_t^{n_t^*+1} < \dots < p_t^N$$

Polling Result

Let n_t^* satisfy $a^{n_t^*-1} < a_t < a^{n_t^*}$

$a^{n_t^*-1}$ = closest “left-wing” alternative.

$a^{n_t^*}$ = closest “right-wing” alternative.

Theorem

Let $\{a_t\}$ be any policy data and $\{p_t^n\}_{t=1, n=1}^{T, N}$ any arbitrary polling data. Then:

1. There exists an α that rationalizes the data iff $\forall t$,

$$1 - p_t^1 < \dots < 1 - p_t^{n_t^*-2} < 1 - p_t^{n_t^*-1} < p_t^{n_t^*} < p_t^{n_t^*+1} < \dots < p_t^N$$

\Rightarrow data restriction

2. Any given α rationalizes the data iff

$$1 - p_t^1 < \dots < 1 - p_t^{n_t^*-2} < 1 - p_t^{n_t^*-1} < \mu(\omega_t, \alpha) < p_t^{n_t^*} < p_t^{n_t^*+1} < \dots < p_t^N$$

Polling Result

Let n_t^* satisfy $a^{n_t^*-1} < a_t < a^{n_t^*}$

$a^{n_t^*-1}$ = closest “left-wing” alternative.

$a^{n_t^*}$ = closest “right-wing” alternative.

Theorem

Let $\{a_t\}$ be any policy data and $\{p_t^n\}_{t=1, n=1}^{T, N}$ any arbitrary polling data. Then:

1. There exists an α that rationalizes the data iff $\forall t$,

$$1 - p_t^1 < \dots < 1 - p_t^{n_t^*-2} < 1 - p_t^{n_t^*-1} < p_t^{n_t^*} < p_t^{n_t^*+1} < \dots < p_t^N$$

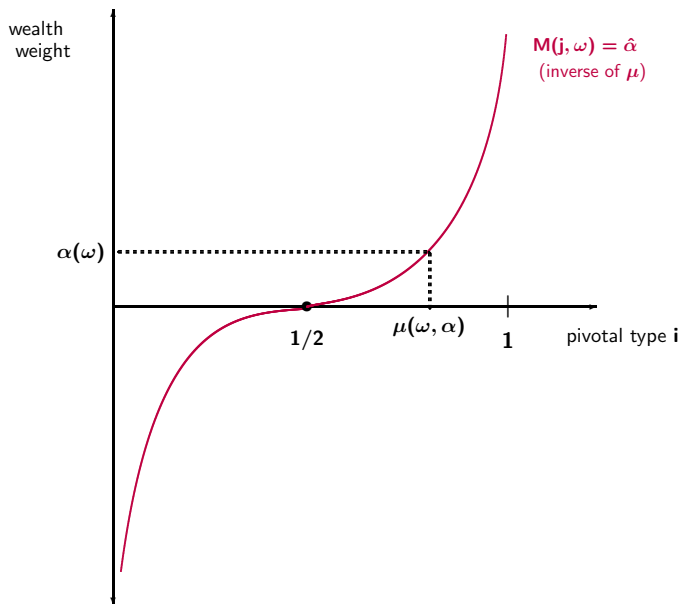
\Rightarrow data restriction

2. Any given α rationalizes the data iff

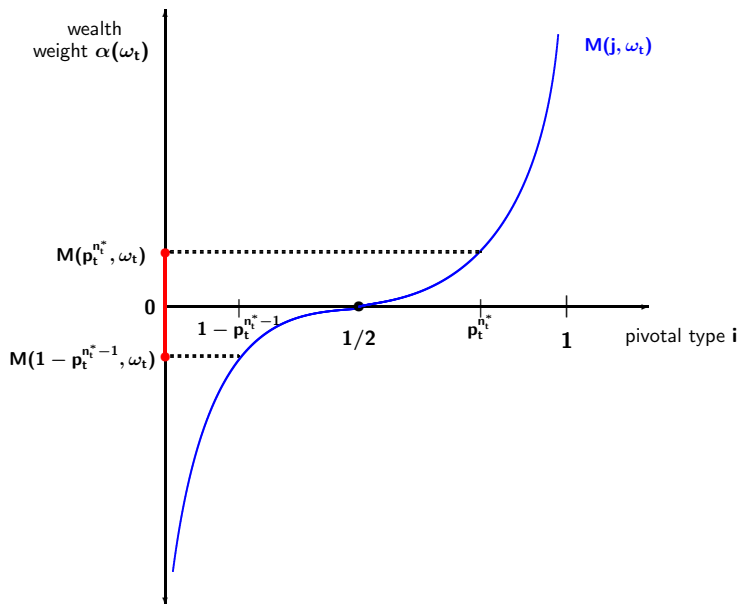
$$1 - p_t^1 < \dots < 1 - p_t^{n_t^*-2} < 1 - p_t^{n_t^*-1} < \mu(\omega_t, \alpha) < p_t^{n_t^*} < p_t^{n_t^*+1} < \dots < p_t^N$$

\Rightarrow bias restriction

Inverse Pivotal Function M



Bias Band



Additional Preference Restrictions

- ▶ For some applied questions, we may have additional information on the preference beyond (A1) and (A2)

Additional Preference Restrictions

- ▶ For some applied questions, we may have additional information on the preference beyond (A1) and (A2)
- ▶ These narrower class of preference may help reveal political wealth bias

Additional Preference Restrictions

- ▶ For some applied questions, we may have additional information on the preference beyond (A1) and (A2)
- ▶ These narrower class of preference may help reveal political wealth bias
- ▶ We illustrate this from two canonical examples:
 - ▶ ω introduces a change in mean income
 - ▶ ω introduces a mean-preserving change of income inequality

Additional Preference Restrictions

Recall our canonical example of public goods provision

$$U(\mathbf{i}, \omega_t, \mathbf{a}_t) = \mathbf{a}_t \mathbf{y}(\mathbf{i}, \omega_t) + \frac{[(1 - \mathbf{a}_t) \bar{y}(\omega_t)]^{1-\rho}}{1 - \rho}.$$

Two interesting cases:

(a) pure growth. $\mathbf{y}(\mathbf{i}, \omega_t) = \mathbf{g}(\mathbf{i})\omega_t$.

The preference satisfies a single-crossing restriction in $(\mathbf{a}; \omega)$

Additional Preference Restrictions

Recall our canonical example of public goods provision

$$U(\mathbf{i}, \omega_t, \mathbf{a}_t) = \mathbf{a}_t \mathbf{y}(\mathbf{i}, \omega_t) + \frac{[(1 - \mathbf{a}_t) \bar{\mathbf{y}}(\omega_t)]^{1-\rho}}{1 - \rho}.$$

Two interesting cases:

(a) pure growth. $\mathbf{y}(\mathbf{i}, \omega_t) = \mathbf{g}(\mathbf{i})\omega_t$.

The preference satisfies a single-crossing restriction in $(\mathbf{a}; \omega)$

(b) pure (mean-preserving) inequality change. $\bar{\mathbf{y}}(\omega) = \bar{\mathbf{y}}$.

The preference only depends on $\mathbf{y}(\mathbf{i}, \omega)$ and \mathbf{a} , i.e.,

$$U(\mathbf{i}, \omega, \mathbf{a}) = u(\mathbf{y}(\mathbf{i}, \omega), \mathbf{a})$$

Additional Single-Crossing Preference Restrictions

(A3) \mathbf{U} satisfies single crossing in the pair $(\mathbf{a}; \omega)$ for each \mathbf{i} .

\implies each citizen's preferred policy rule is incr. in the state.

Theorem

A weighting function α rationalizes $\{\mathbf{a}_t\}$ with preference in (A1)-(A3) iff for any pair of observed states such that $\omega_t > \omega_\tau$,

$$\mathbf{a}_t < \mathbf{a}_\tau \implies \mu(\omega_t, \alpha) < \mu(\omega_\tau, \alpha)$$

Additional Single-Crossing Preference Restrictions

(A3) \mathbf{U} satisfies single crossing in the pair $(\mathbf{a}; \omega)$ for each \mathbf{i} .

\implies each citizen's preferred policy rule is incr. in the state.

Theorem

A weighting function α rationalizes $\{\mathbf{a}_t\}$ with preference in (A1)-(A3) iff for any pair of observed states such that $\omega_t > \omega_\tau$,

$$\mathbf{a}_t < \mathbf{a}_\tau \implies \mu(\omega_t, \alpha) < \mu(\omega_\tau, \alpha)$$

Corollary

The unbiased weighting system rationalizes the policy data only if the data is wkly increasing in the state.

Additional Separable Preference Restrictions

$$(A4) \mathbf{U}(\mathbf{i}, \omega, \mathbf{a}) = \mathbf{u}(\mathbf{y}(\mathbf{i}, \omega), \mathbf{a}).$$

\implies each citizen's preferred policy rule is incr. in the income.

Additional Separable Preference Restrictions

$$(A4) \quad U(\mathbf{i}, \omega, \mathbf{a}) = u(\mathbf{y}(\mathbf{i}, \omega), \mathbf{a}).$$

\implies each citizen's preferred policy rule is incr. in the income.

Theorem

A weighting function α rationalizes $\{\mathbf{a}_t\}$ with preference in (A1), (A2) and (A4) iff for any pair of observations,

$$\mathbf{a}_t < \mathbf{a}_\tau \implies \mathbf{y}(\mu(\omega_t, \alpha), \omega_t) < \mathbf{y}(\mu(\omega_\tau, \alpha), \omega_\tau)$$

Additional Separable Preference Restrictions

(A4) $U(\mathbf{i}, \omega, \mathbf{a}) = u(\mathbf{y}(\mathbf{i}, \omega), \mathbf{a})$.

\implies each citizen's preferred policy rule is incr. in the income.

Theorem

A weighting function α rationalizes $\{\mathbf{a}_t\}$ with preference in (A1), (A2) and (A4) iff for any pair of observations,

$$\mathbf{a}_t < \mathbf{a}_\tau \implies \mathbf{y}(\mu(\omega_t, \alpha), \omega_t) < \mathbf{y}(\mu(\omega_\tau, \alpha), \omega_\tau)$$

Corollary

The unbiased weighting system rationalizes the policy data iff a policy change is associated with a change of the median income in the same direction.

Conclusions

1. Toward a formal theory of revealed political power.
2. Policy data alone with only weak preference requirement is not discerning.
3. Policy + polling data jointly describe the boundaries of wealth bias.
4. Additional preference restrictions rule out some types of bias.
5. **Biggest challenge:** Multi-dimensional policy and state spaces. Some success with order restricted preferences, but inherent difficulties.

Single Crossing in (\mathbf{i}, \mathbf{a}) :

For all $\mathbf{a} > \hat{\mathbf{a}}$,

$$\mathbf{U}(\mathbf{i}, \omega_t, \mathbf{a}) - \mathbf{U}(\mathbf{i}, \omega_t, \hat{\mathbf{a}}) > 0$$

implies

$$\mathbf{U}(\mathbf{j}, \omega_t, \mathbf{a}) - \mathbf{U}(\mathbf{j}, \omega_t, \hat{\mathbf{a}}) > 0 \quad \forall \mathbf{j} > \mathbf{i}.$$

Two Interpretations

1. A Classic Static RPT Interpretation

The observer sees $\{\mathbf{a}_t, \omega_t\}_{t=1}^T$. No intertemporal connection. Data is a time series generated by myopic citizens.

Two Interpretations

1. A Classic Static RPT Interpretation

The observer sees $\{\mathbf{a}_t, \omega_t\}_{t=1}^T$. No intertemporal connection. Data is a time series generated by myopic citizens.

2. A Dynamic Economy Interpretation

The observer sees $\{\mathbf{a}_t, \omega_t\}_{t=1}^T$. He infers intertemporal connections, backing out transition rule $\omega_{t+1} = \mathbf{Q}(\omega_t, \mathbf{a}_t)$. Data is generated by forward looking citizens (\mathbf{U} is a long run payoff). Underlying time horizon is infinite.

The Political Side

Power is measured by a *wealth-weighted vote share* $\lambda(\mathbf{y}, \boldsymbol{\alpha}, \boldsymbol{\omega})$
where $\boldsymbol{\alpha}(\boldsymbol{\omega}) = \textit{bias}$ in each state.

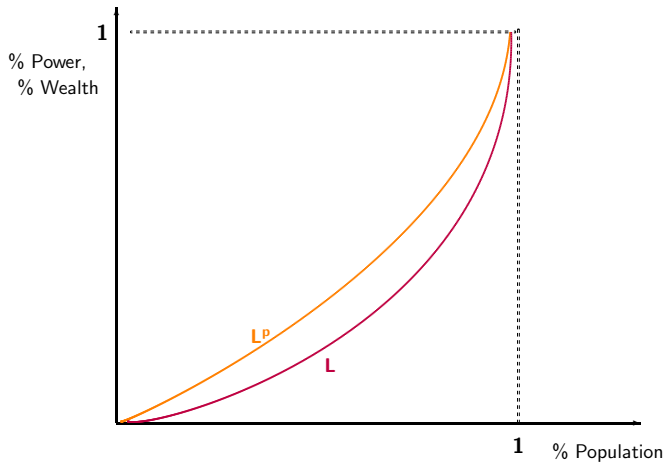
The Political Side

Power is measured by a *wealth-weighted vote share* $\lambda(\mathbf{y}, \alpha, \omega)$ where $\alpha(\omega) = \textit{bias}$ in each state.

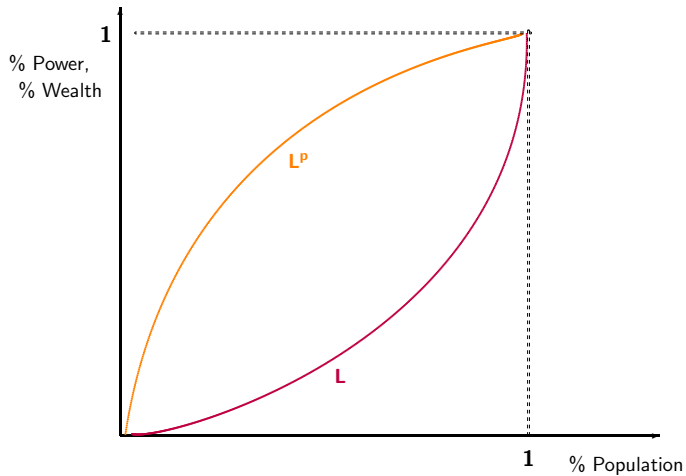
- ▶ λ is a density in income \mathbf{y} .
- ▶ λ is increasing in income if $\alpha > \mathbf{0}$, decreasing in income if $\alpha < \mathbf{0}$; constant if $\alpha = \mathbf{0}$.
- ▶ λ satisfies strict single crossing in $(\alpha; \mathbf{y})$ and $\rightarrow \mathbf{0}$ as $\alpha \rightarrow \pm\infty$

Observer knows $\lambda(\cdot)$ but must infer $\alpha(\cdot)$ from data.

Political Lorenz Curve with Dampened Elitist Bias



Political Lorenz Curve with Populist Bias



Algorithm

Necessity is the easy part. Sufficiency is harder.

Step 1^o Use a recursive algorithm to construct $\tilde{\Psi}(\mathbf{i}, \omega)$ satisfying

1. $\tilde{\Psi}(\mu(\omega_t, \alpha), \omega_t) = \mathbf{a}_t \quad \forall t = 1, \dots, T.$
2. $\tilde{\Psi}(\mathbf{i}, \omega)$ increasing in \mathbf{i} and ω .

Step 2^o Use the constructed $\tilde{\Psi}$ to define Ψ and \mathbf{U} given by

$$\mathbf{U}(\mathbf{i}, \omega, \mathbf{a}; \Psi) = -\frac{1}{2} \left(\mathbf{a} - \tilde{\Psi}(\mathbf{i}, \omega) \right)^2,$$